

SOLOW WITH LABOR AUGMENTING
TECHNOLOGICAL CHANGE

PROD. FUNCTION

(1) $Y = k^{\alpha} (AL)^{1-\alpha}$ $0 < \alpha < 1$, $A > 0$

↑
TECHNOLOGICAL LEVEL A

WE CAN THINK OF "AL" AS THE "EFFECTIVE" AMOUNT OF LABOR USED IN PRODUCTION

(2) $\hat{A} = g > 0$ RATE OF TECHNOLOGICAL CHANGE

CONS / SAVINGS

(3) $S = \alpha \cdot Y$ $0 < \alpha < 1$

ASSUME $I = S$ \Rightarrow

$Y = C + I \Rightarrow$

$C = (1 - \alpha) Y$

POPULATION = # WORKERS AND
LABOR FORCE

(4) $\hat{L} = n$ RATE OF POP. GROWTH

LAW OF MOTION OF k

DEPRECIATION RATE

(5) $\dot{k} = s - \delta k$ $0 < \delta < 1$

USING (12) & EQUILIBRIUM CONDITION ($S = I$)

(6) $\dot{k} = \alpha \cdot Y - \delta k$
SINCE $\hat{k} = \dot{k} / k \Rightarrow$

(7) $\hat{k} = \frac{\alpha Y}{k} - \delta$

△ BGP:

(2)

ALONG BGP, ALL VARIABLES GROW AT CONSTANT RATES, i.e.

$$\hat{k} \text{ CONST}, \hat{y} \text{ CONSTANT}, \dots$$

• FROM (17):

$$\hat{k} = \frac{\alpha Y}{k} - \delta$$

WE HAVE THAT ALONG A BGP:

$$\frac{Y}{k} \text{ CONSTANT} \Rightarrow \boxed{\hat{y} = \hat{k}} \quad (*)$$

• WE TAKE GROWTH RATES ON (10):

$$Y = k^\alpha (AL)^{1-\alpha}$$

$$\hat{y} = \alpha \hat{k} + (1-\alpha)(\hat{A} + \hat{L})$$

USING (*)

$$\hat{y} = \hat{k}$$

$$\hat{y} (1-\alpha) = (1-\alpha)(\hat{A} + \hat{L}) \Rightarrow \hat{y} = \hat{A} + \hat{L} = g + n$$

USING (2) & (4)

$$(*) \quad \boxed{\hat{y} = g + n} \quad \boxed{= \hat{k}}$$

NOTICE THAT THIS IMPLIES THAT ALONG

A BGP: $\frac{k}{AL}$, $\frac{Y}{AL}$ ARE CONSTANT

THEN WE CAN PERFORM A CHANGE OF VARIABLES ALONG THESE LINES AND THE MODIFIED SYSTEM WILL HAVE A STEADY STATE (THAT

COINCIDES WITH THE BGP OF THE ORIGINAL VARIABLES)

CHANGE OF VARIABLE

NEW VARIABLES:

OUTPUT PER EFFECTIVE UNIT OF LABOR

$$\tilde{y} = \frac{Y}{AL} = \frac{y}{A}$$

$$\tilde{c} = \frac{C}{AL} = \frac{c}{A}$$

CAPITAL PER EFFECTIVE UNIT OF LABOR

$$\tilde{m} = \frac{k}{AL} = \frac{m}{A}$$

WE WILL LOOK AT THE SYSTEM IN THE MODIFIED VARIABLES \Rightarrow NEED TO CALCULATE PROD. FUNCTION IN MODIFIED VARIABLES AND LAW OF MOTION OF \tilde{m} .

(i) PROD. FUNCTION.

DIVIDE (10) BY AL

$$\frac{Y}{AL} = \frac{k^\alpha (AL)^{1-\alpha}}{AL} = \frac{k^\alpha (AL)^{1-\alpha}}{(AL)^\alpha (AL)^{1-\alpha}} = \left(\frac{k}{AL}\right)^\alpha$$

i.e.

$$(10) \quad \tilde{y} = \tilde{m}^\alpha$$

(ii) LAW OF MOTION OF \tilde{m}

SINCE $\tilde{m} = \frac{k}{AL}$ USING NAT ALGEBRA:

$$\hat{\tilde{m}} = \hat{k} - \hat{A} - \hat{L} = \hat{k} - (\delta + n)$$

USING (7)

$$\hat{\tilde{m}} = \alpha \frac{\hat{Y}}{k} - \delta - (g+n) = \frac{\alpha \frac{Y}{AL}}{k/AL} - (\delta + n)$$

DIVIDING/MULTY 1ST TERM BY AL

$$\hat{\tilde{h}}_n = a \frac{\tilde{h}_n^d}{\tilde{h}_n} - (d+g+n)$$

using (10)

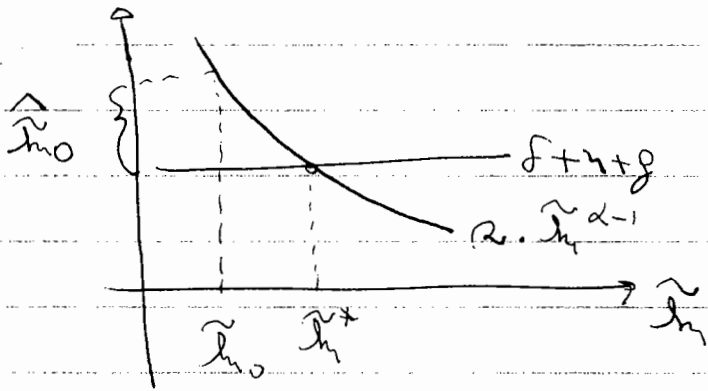
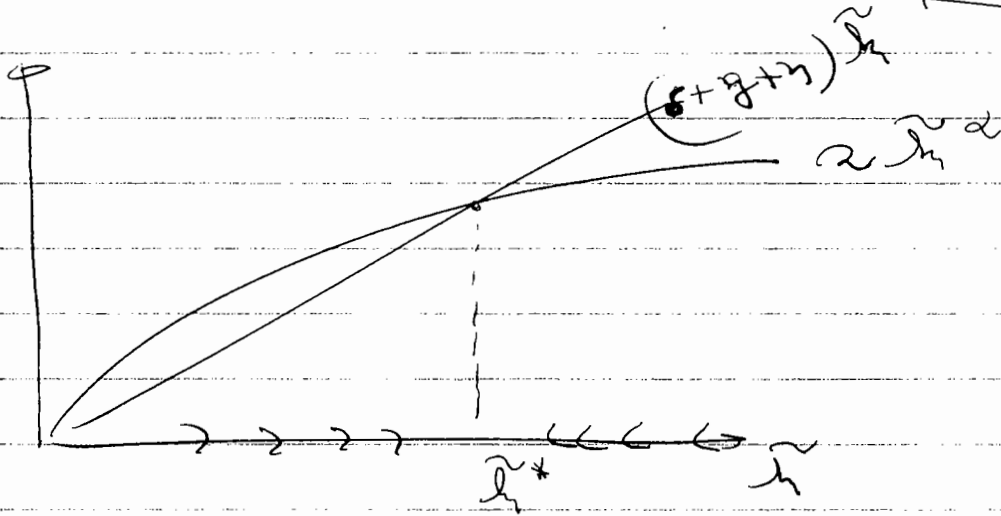
$$(11) \quad \boxed{\hat{\tilde{h}}_n} = a \frac{\tilde{h}_n^d}{\tilde{h}_n} - (d+g+n) = \boxed{a \tilde{h}_n^{d-1} - (d+g+n)}$$

since $\hat{\tilde{h}}_n = \dot{\tilde{h}}_n / \tilde{h}_n \Rightarrow \dot{\tilde{h}}_n = \hat{\tilde{h}}_n \cdot \tilde{h}_n$

AND

$$(12) \quad \boxed{\dot{\tilde{h}}_n = a \tilde{h}_n^{d-1} - (d+g+n) \tilde{h}_n}$$

Low
Equation



NOTICE:
 h^{*} is the
 S.S.
 AND
 $\hat{h}^{*} = 0$

ANALYSIS OF SYSTEM

THE MODIFIED SYSTEM HAS A S.S. AT \tilde{h}^*

SINCE $\hat{\tilde{h}}^* = 0$

(I)

IF $\tilde{h} < \tilde{h}^* \Rightarrow \hat{\tilde{h}} > 0$ & $\tilde{h} \uparrow$

IF $\tilde{h} > \tilde{h}^* \Rightarrow \hat{\tilde{h}} < 0$ & $\tilde{h} \downarrow$

i.e. NO MATTER WHERE WE START WE END UP AT S.S.

SINCE $\hat{\tilde{y}} = \alpha \hat{\tilde{h}}$

(BY TAKING GROWTH RATES OF (10))

WE HAVE

$\hat{\tilde{y}}^* = 0$ AT S.S.

IF $\tilde{y} < \tilde{y}^* \Rightarrow \hat{\tilde{y}} > 0 \Rightarrow \tilde{y} \uparrow$

IF $\tilde{y} > \tilde{y}^* \Rightarrow \hat{\tilde{y}} < 0 \Rightarrow \tilde{y} \downarrow$

NOTICE THAT THE S.S. OF MODIFIED SYSTEM IS

THE BGP OF ORIGINAL ONE -

AT S.S. $\hat{\tilde{y}} = \left(\frac{\hat{y}}{AC} \right) = 0 \Rightarrow \left(\frac{\hat{y}}{z} \right) = A$

OR

$\boxed{\hat{\tilde{y}}} = A = \boxed{\hat{y}}$

SO OUTPUT PER WORKER GROWS AT THE RATE OF TECH. CHANGE

(II)

LEVELS

AT S.S. $\hat{\tilde{h}} = 0 \Rightarrow$ BY (11) THAT $0 = \alpha \tilde{h}^{* \alpha - 1} - (\delta + \eta)$

$\Rightarrow \alpha \tilde{h}^{* \alpha - 1} = \delta + \eta$

$$\left(\frac{\alpha}{\delta + \rho + n}\right)^{\frac{1}{1-\alpha}} = \tilde{h}^* \Rightarrow \tilde{y}^* = \left(\frac{\alpha}{\delta + \rho + n}\right)^{\frac{\alpha}{1-\alpha}} \tilde{h}^* \quad (13) \quad (6)$$

↓ using (10)

SINCE $\tilde{y}^* = \frac{y_t^*}{A_t} \Rightarrow y_t^* = A_t \tilde{y}^*$

i.e. using (13)

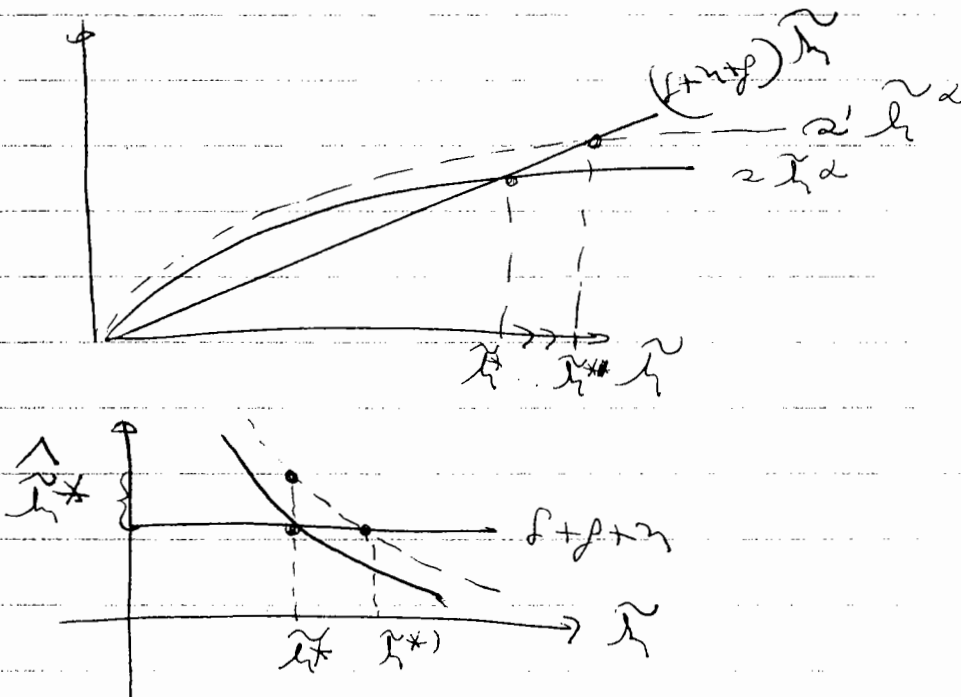
$$y_t^* = \left(\frac{\alpha}{\delta + \rho + n}\right)^{\frac{\alpha}{1-\alpha}} A_t$$

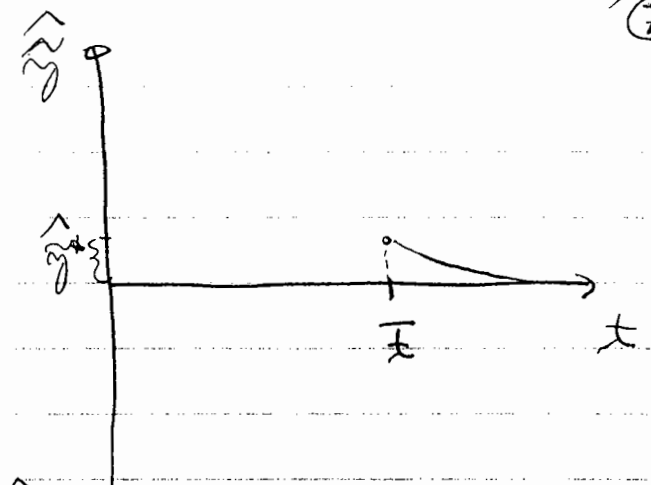
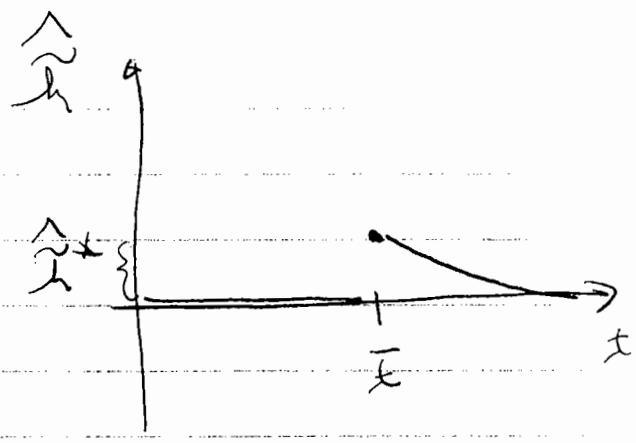
ALONG A SSP OUTPUT PER WORKER
FOLLOWS THIS PATH

COMPARATIVE STATICS

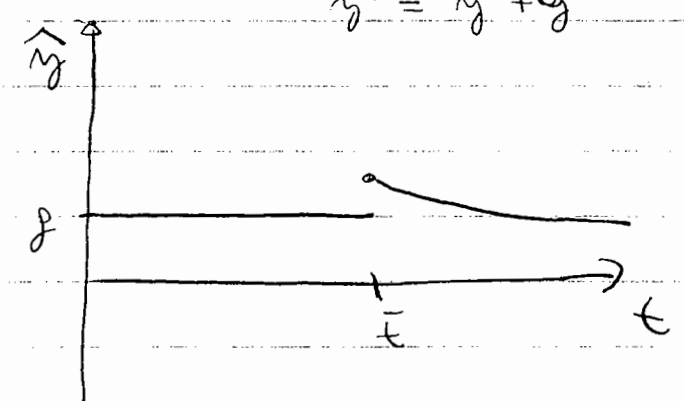
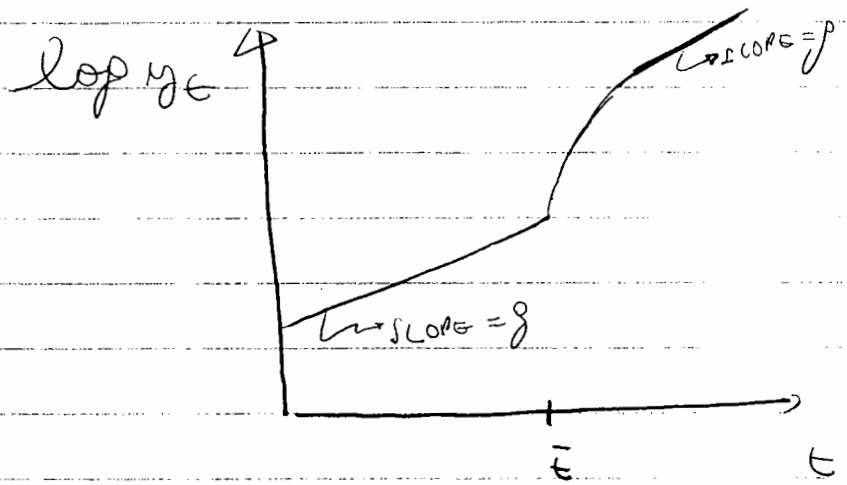
(EFFECT ON PATH OF
OUTPUT PER WORKER)

(1) $\uparrow \alpha$: EFFECTS ON \hat{y}_t & y_t





SINCE $\hat{y} = \alpha \hat{h}$ AND $\hat{y} = \gamma/A \Rightarrow \hat{y} = \hat{h} + g$



NOTICE SLOPE OF $\log y_t$ BIGGER THAN g DURING ADJUSTMENT PERIOD.