

Econ 879: Topics in Dynamic Economics

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Mathematical Preliminaries

- σ -algebra: Let Ω be a set. A class \mathcal{F} of subsets of Ω is a σ -algebra if:
 - $A \in \mathcal{F} \rightarrow A^c \in \mathcal{F}$.
 - $A, B \in \mathcal{F} \rightarrow A \cup B \in \mathcal{F}$.
 - $\Omega \in \mathcal{F}$ ($\emptyset \in \mathcal{F}$)
 - if $A_i \in \mathcal{F}$, $i = 1, 2, \dots$ then $\bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$.
- A set $A \in \mathcal{F}$ is called measurable.

- Example: Toss a coin twice. In this case

$$\Omega = \{(H, H), (H, T), (T, H), (T, T)\}$$

Let \mathcal{F}_a be given by

$$\mathcal{F}_a = \{\Omega, \emptyset, \{(H, H), (H, T)\}, \{(T, H), (T, T)\}\}$$

Is it a σ -algebra?

- Example: Let \mathcal{F}_b be given by

$$\mathcal{F}_b = \{\Omega, \emptyset, \{(H, H)\}, \{(H, T), (T, H), (T, T)\}\}$$

Is it a σ -algebra?

Theorem 1 (Monotone Convergence I) *Let Y, X_1, X_2, \dots be random variables.*

1. *If $X_n \geq Y$, for all $n \geq 1$ and $E[Y] > -\infty$ and $X_n \nearrow X$, then $E[X_n] \nearrow E[X]$.*
2. *If $X_n \leq Y$, for all $n \geq 1$ and $E[Y] < \infty$ and $X_n \searrow X$, then $E[X_n] \searrow E[X]$.*

Theorem 2 (Monotone Convergence II) *Let X_1, X_2, \dots be random variables. Then if $X_n \leq X_{n+1}$ then*

$$\int \lim_{n \rightarrow \infty} X_n d\mu = \lim_{n \rightarrow \infty} \int X_n d\mu.$$

Theorem 3 (Monotone Convergence III) *Let X_1, X_2, \dots be random variables. Then if $X_n \leq X_{n+1}$ and if*

$$\int X_n d\lambda \leq B$$

for some B . Then there exists a random variable X such that $X_n \rightarrow X$, λ -a.s. and

$$\lim_{n \rightarrow \infty} \int X_n d\lambda = \int X d\lambda$$

Theorem 4 (Fatou's lemma) *Let Y, X_1, X_2, \dots be random variables.*

1. *If $X_n \geq Y$, for all $n \geq 1$ and $E[Y] > -\infty$, then $E[\underline{\lim} X_n] \leq \underline{\lim} E[X_n]$.*
2. *If $X_n \leq Y$, for all $n \geq 1$ and $E[Y] < \infty$, then $\overline{\lim} E[X_n] \leq E[\overline{\lim} X_n]$.*
3. *If $|X_n| \leq Y$, for all $n \geq 1$ and $E[Y] < \infty$, then $E[\underline{\lim} X_n] \leq \underline{\lim} E[X_n] \leq \overline{\lim} E[X_n] \leq E[\overline{\lim} X_n]$.*

Theorem 5 (Lebesgue Dominated Convergence) *Let Y, X_1, X_2, \dots be random variables such that $|X_n| \leq Y$, $E[Y] < \infty$, and $X_n \xrightarrow{a.s.} X$, then*

1. $E[|X|] < \infty$
2. $E[|X_n|] \rightarrow E[X]$
3. $E[|X_n - X|] \rightarrow 0$.

Corollary 6 *Let Y, X_1, X_2, \dots be random variables such that $|X_n| \leq Y$, $E[Y^p] < \infty$, for some $p > 0$, and $X_n \xrightarrow{a.s.} X$, then $E[|X|^p] < \infty$ and $E[|X_n - X|^p] \rightarrow 0$.*

Theorem 7 (Fubini) *Let $X = X(\omega_1, \omega_2)$ be an $\mathcal{F}_1 \otimes \mathcal{F}_2$ measurable function, integrable with respect to the measure $\mu_1 \times \mu_2$. Then*

1. *The integrals*

$$\int_{\Omega_1} X(\omega_1, \omega_2) \mu_1(d\omega_1)$$

$$\int_{\Omega_2} X(\omega_1, \omega_2) \mu_2(d\omega_2)$$

are defined for all (ω_1, ω_2) , and they are \mathcal{F}_2 and \mathcal{F}_1 measurable.

2. $\mu_2\{\omega_2 : \int_{\Omega_1} |X(\omega_1, \omega_2)| \mu_1(d\omega_1) = \infty\} = 0$, and $\mu_1\{\omega_1 : \int_{\Omega_2} |X(\omega_1, \omega_2)| \mu_2(d\omega_2) = \infty\} = 0$, and

$$\int_{\Omega_1 \times \Omega_2} X(\omega_1, \omega_2) \mu_1 \times \mu_2(d\omega_1, d\omega_2) = \int_{\Omega_1} \left[\int_{\Omega_2} X(\omega_1, \omega_2) \mu_2(d\omega_2) \right] \mu_1(d\omega_1)$$

$$= \int_{\Omega_2} \left[\int_{\Omega_1} X(\omega_1, \omega_2) \mu_1(d\omega_1) \right] \mu_2(d\omega_2).$$

Remark 8 If $\Omega_1 = [0, \infty)$, and $\mathcal{F}_1 = \mathcal{B}(\mathfrak{R})$, $\mu_1 = \text{Lebesgue}$, and $\mu_2, \Omega_2, \mathcal{F}_2$ arbitrary it says that if

$$E \left[\int_0^\infty |X(t, \omega)| dt \right] < \infty$$

then,

$$E \left[\int_0^\infty X(t, \omega) dt \right] = \int_0^\infty E[X(t, \omega)] dt$$

Theorem 9 (Tonelli) *If $X(t, \omega) \geq 0$ and*

$$\int_{[0, \infty) \times \Omega} X(t, \omega) \lambda \times \mu(dt, d\omega)$$

is defined (but it could be infinite), we still have

$$E \left[\int_0^\infty X(t, \omega) dt \right] = \int_0^\infty E[X(t, \omega)] dt$$

although it could be equal to infinity.

- Let Ω be a space of events, or sample space, and P a probability measure. Let \mathcal{F} be σ -algebra of subsets. Let $S \subseteq \mathfrak{R}^d$ be the state space, and \mathcal{S} the Borel σ -algebra. A stochastic process is a function

$$X : [0, \infty) \times \Omega \rightarrow S$$

such that, for each t , $X(t, \bullet)$ is \mathcal{F} -measurable. The mapping

$$X(\bullet, \omega) : [0, \infty) \rightarrow S$$

is a sample path.

- $X(t, \bullet)$ is \mathcal{F} -measurable means that $B \in \mathcal{S} \rightarrow \{\omega : X(t, \omega) \in B\} \in \mathcal{F}$.

Definition 10 (Filtration) A filtration is a non-decreasing family of sub σ -fields of \mathcal{F} , $\mathcal{F}_s \subseteq \mathcal{F}_t$, for $0 \leq s \leq t < \infty$. Let $\mathcal{F}_\infty = \sigma(\cup_{t \geq 0} \mathcal{F}_t)$

$$\mathcal{F}_{t-} \equiv \sigma(\cup_{s < t} \mathcal{F}_s),$$

$$\mathcal{F}_{t+} \equiv \cap_{\epsilon > 0} \mathcal{F}_{t+\epsilon}$$

A filtration is right continuous if $\mathcal{F}_t = \mathcal{F}_{t+}$.

Definition 11 (Adapted) A process X is adapted to $\{\mathcal{F}_t\}$ if X_t is \mathcal{F}_t -measurable

- Example: Coin toss. In this case

$$\Omega = \{(H, H), (H, T), (T, H), (T, T)\}$$

Let's consider the natural filtration, i.e. the filtration generated by each coin toss. Before we toss the coin, \mathcal{F}_0 is

$$\mathcal{F}_0 = \{\Omega, \emptyset, \Omega\}.$$

After the first toss (at time $t = 1$) the information available (i.e. whether the first toss is a head or a tail) is summarized by \mathcal{F}_1 where

$$\mathcal{F}_1 = \{\Omega, \emptyset, \{(H, H), (H, T)\}, \{(T, H), (T, T)\}\}.$$

After the second toss (i.e. in the second period) we have that

$$\begin{aligned} \mathcal{F}_2 = & \{\Omega, \emptyset, \{(H, H), (H, T)\}, \{(T, H), (T, T)\}, \\ & \{(H, H)\}, \{(H, T)\}, \{(T, H)\}, \{(T, T)\}, \\ & \text{plus other sets}\} \end{aligned}$$

- Let X be $\{\mathcal{F}_t\}$ adapted. Then, it must be the case that be given by

$$X_1(H, H) = X_1(H, T) = x_1^H,$$

and

$$X_1(T, H) = X_1(T, T) = x_1^T.$$

In this case

$$\begin{aligned} X_1^{-1}(x_1^H) &= \{(H, H), (H, T)\} \in \mathcal{F}_1, \\ X_1^{-1}(x_1^T) &= \{(T, H), (T, T)\} \in \mathcal{F}_1. \end{aligned}$$

- Let Y be such that

$$\begin{aligned} Y_1(H, H) &= 1, \\ Y_1(H, T) &= Y_1(T, H) = Y_1(T, T) = 0, \end{aligned}$$

and

$$Y_2(\omega) = Y_1(\omega).$$

Is $Y \{\mathcal{F}_t\}$ adapted?

- Is Y \mathcal{F}_b measurable?

$$\mathcal{F}_b = \{\Omega, \emptyset, \{(H, H)\}, \{(H, T), (T, H), (T, T)\}\}$$

Definition 12 (Stopping Time) Let (Ω, \mathcal{F}) be a measurable space equipped with the filtration $\{\mathcal{F}_t\}$. A random time T is a stopping time of the filtration if

$$\{\omega : T(\omega) \leq t\} \in \mathcal{F}_t.$$

It is called **optional time** if

$$\{\omega : T(\omega) < t\} \in \mathcal{F}_t.$$

It follows that all constants are stopping times and if $\{\mathcal{F}_t\}$ is right continuous every stopping time is optional (exercise).

There is a special class of stopping times denoted *hitting times*. Let $\Gamma \in \mathcal{B}(R^d)$ and let

$$H_\Gamma(\omega) = \inf\{t \geq 0; X_t(\omega) \in \Gamma\}$$

Results:

- If Γ is open then H_Γ is optional.
- If Γ is closed and the sample paths of X are continuous, then H_Γ is a stopping time.

1. T optional and $\theta > 0$ implies that $T + \theta$ is a stopping time.

2. T and S stopping times \rightarrow

$$T \wedge S$$

$$T \vee S$$

$$T + S$$

are stopping times

3. T and S optional times $\rightarrow T + S$ optional. $T + S$ is a stopping time if either

a) $T > 0, S > 0,$

b) $T > 0, T$ is a stopping time

4. $\{T_n\}$ sequence of stopping times so is $\sup_{n \geq 1} T_n$.

Definition 13 Let T be a stopping time of the filtration $\{\mathcal{F}_t\}$. The σ -field \mathcal{F}_T of events determined prior to the stopping time T consists of those events $A \in \mathcal{F}$ for which

$$\text{for all } t, \quad A \cap \{T \leq t\} \in \mathcal{F}_t$$

- If $T = t$ then $\mathcal{F}_T = \mathcal{F}_t$.
- Let T be a stopping time and S a random time such that $S \geq T$. If S is \mathcal{F}_T -measurable it is also a stopping time.
- Let T and S be stopping times. For any $A \in \mathcal{F}_S$

$$A \cap \{S \leq T\} \in \mathcal{F}_T.$$

In particular, if $S \leq T \rightarrow \mathcal{F}_S \subseteq \mathcal{F}_T$.

- Let T and S be stopping times. Then,

$$\mathcal{F}_{T \wedge S} = \mathcal{F}_T \cap \mathcal{F}_S,$$

and each of the following events

$$\{T < S\},$$

$$\{S < T\},$$

$$\{T \leq S\},$$

$$\{T = S\},$$

belongs to $\mathcal{F}_{T \wedge S} = \mathcal{F}_T \cap \mathcal{F}_S$.

Definition 14 (Progressively Measurable) X is called progressively measurable with respect to $\{\mathcal{F}_t\}$ if for all $t \geq 0$ and $A \in \mathcal{B}(\mathbb{R}^d)$ the set

$$\{(s, \omega) : 0 \leq s \leq t, \omega \in \Omega, X_s(\omega) \in A\}$$

belongs to the product σ -field $\mathcal{B}([0, t]) \otimes \mathcal{F}_t$.

Definition 15 (Usual Conditions) A Filtration $\{\mathcal{F}_t\}$ satisfies the usual conditions if it is right continuous and \mathcal{F}_0 contains all the P – null sets in \mathcal{F} .

Proposition 16 If the process X has RCLL paths and is adapted to the filtration $\{\mathcal{F}_t\}$ which satisfies the usual conditions, then there exists a sequence of stopping times $\{T_n\}$ which exhausts the jumps of X , i.e.

$$\{(t, \omega) : X_t(\omega) \neq X_{t-}(\omega)\} \subseteq \cup_{n=1}^{\infty} \{(t, \omega) : T_n(\omega) = t\}$$

Continuous Time Martingales

- Maintained assumptions:

1. (Ω, \mathcal{F}, P) is a probability space.

2. $\{\mathcal{F}_t\}$ is a filtration (to which X_t is adapted)

3. $E[|X_t|] < \infty$, for all $t \geq 0$.

Definition 17 (Submartingale-Supermartingale-Martingale) X is a submartingale (supermartingale) if for all $0 \leq s < t < \infty$ we have P -a.s.

$$\begin{aligned} X_s &\leq E[X_t | \mathcal{F}_s] \\ (X_s &\geq E[X_t | \mathcal{F}_s]). \end{aligned}$$

If X is both a sub and a supermartingale then it is a martingale

Inequalities

- Let X be a submartingale and let $\mathcal{F}_\infty = \sigma(\cup_{t \geq 0} \mathcal{F}_t)$, then it follows that if there exists an \mathcal{F}_∞ -measurable random variable, X_∞ , such that

$$X_t \leq E[X_\infty | \mathcal{F}_t], \quad t \geq 0, \quad P - a.s.,$$

then we say that $\{X_t, \{\mathcal{F}_t\}, 0 \leq t \leq \infty\}$ is a submartingale with *last element* X_∞ .

- This also applies to martingales

Convergence Results

- Assume that all processes are *right continuous*.

Theorem 18 (Submartingale Convergence) Let $\{X_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ be a right continuous submartingale. If

$$C \equiv \sup_{t \geq 0} E[X_t^+] < \infty,$$

then

$$X_\infty(\omega) \equiv \lim_{t \rightarrow \infty} X_t(\omega) \quad \text{exists } P - \text{as,}$$
$$E[| X_\infty |] < \infty.$$

where

$$X_t^+ = \max\{X_t, 0\}$$

- If the submartingale is **non-negative** then the existence part is guaranteed without any further assumptions and

$$\{X_t, \{\mathcal{F}_t\}, 0 \leq t \leq \infty\}$$

is a submartingale.

- If instead of a submartingale we have a supermartingale then the analogous conditions/results are

$$C \equiv \sup_{t \geq 0} E[X_t^-] < \infty,$$

then

$$X_\infty(\omega) \equiv \lim_{t \rightarrow \infty} X_t(\omega) \quad \text{exists } P - \text{as,}$$

$$E[| X_\infty |] < \infty.$$

where

$$X_t^- = \max\{-X_t, 0\}$$

Definition 19 (Uniform Integrability) A collection of random variables $\{X_t\}$ defined on (Ω, \mathcal{F}, P) is uniformly integrable if

$$\int_{\{|X_t| \geq c\}} |X_t(\omega)| dP(\omega)$$

converges to 0, uniformly in t , as $c \rightarrow \infty$.

Definition 20 (L^1 norm) $\|X_t\|_1 \equiv \int |X_t(\omega)| dP(\omega)$, provided it is finite.

- If $\{X_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ is a **uniformly integrable** supermartingale then,

$$\sup_t \|X_t\|_1 < \infty,$$

and since $E[X_t^-] \leq \|X_t\|_1$ the supermartingale version of the theorem implies

$$X_\infty(\omega) \equiv \lim_{t \rightarrow \infty} X_t(\omega) \quad \text{exists } P - \text{as.}$$

By uniform integrability convergence is also in $L^1 \rightarrow \{X_t, \{\mathcal{F}_t\}, 0 \leq t \leq \infty\}$ is also a supermartingale!

Theorem 21 (Optional Sampling) *Let $\{X_t, \{\mathcal{F}_t\}, 0 \leq t \leq \infty\}$ be a right continuous submartingale with last element X_∞ and let $S \leq T$ be two optional times of the filtration $\{\mathcal{F}_t\}$. Then,*

1.

$$X_S \leq E[X_T \mid \mathcal{F}_{S^+}], \quad t \geq 0, \text{ } P - \text{as},$$

2. *If S is a stopping time then*

$$X_S \leq E[X_T \mid \mathcal{F}_S], \quad t \geq 0, \text{ } P - \text{as},$$

and, in particular,

$$E[X_0] \leq E[X_T].$$

3. For a martingale with last element X_∞ the previous inequalities are equalities.

- **Note:** the theorem assumes that the process has a last element X_∞ . This is a strong assumption. See before to check the iff conditions for this!

- Example: Gambling.

- Example:

$$X_t = \sum_{j=1}^t Z_j, \quad Z_j \in \{-1, 1\}, \quad p = 1/2,$$
$$X_0 = 0,$$

and

$$T = \inf\{t : X_t = 1\}$$

- Is it necessary for the process to have a last element?
 - Alternative conditions under which the theorem holds
1. Let $\{X_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ be a right continuous submartingale and let the **optional** times satisfy $S \leq T$, then OST holds if either of these two conditions is satisfied:
 - (a) T is bounded (i.e. $\exists a$ such that $T(\omega) \leq a$ $P - a.s$)
 - (b) There exists an integrable random variable Y such that $X_t \leq E[Y | \mathcal{F}_t], \quad t \geq 0, P - a.s.$
 2. Let $\{X_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ be a right continuous submartingale and let the **stopping** times satisfy $S \leq T$, then

(a) $\{X_{T \wedge t}, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ is a submartingale,

(b)

$$X_{S \wedge t} \leq E[X_{T \wedge t} \mid \mathcal{F}_{S \wedge t}], \quad t \geq 0, \quad P - a.s.$$

3. A submartingale of constant expectation, $E[X_t] = E[X_0]$ is a martingale.

4. Let $\{X_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ be a right continuous process with

$$E[|X_t|] < \infty, \quad 0 \leq t < \infty,$$

then this process is a submartingale iff for every pair of stopping times $S \leq T$ of the filtration $\{\mathcal{F}_t\}$ we have

$$E[X_S] \leq E[X_T].$$

5. Let T be a bounded stopping time of the filtration $\{\mathcal{F}_t\}$ which satisfies the usual conditions. Let

$$\tilde{\mathcal{F}}_t \equiv \mathcal{F}_{T+t}$$

then $\tilde{\mathcal{F}}_t$ also satisfies the usual conditions and

(a) If $\{X_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ is a right continuous submartingale then so is

$$\tilde{X}_t = X_{T+t} - X_T$$

for the filtration $\{\tilde{\mathcal{F}}_t\}$.

(b) If $\{\tilde{X}_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ is a right continuous submartingale with $\tilde{X}_0 = 0$ *P*-*as* then

$$X_t = \tilde{X}_{(t-T) \vee 0}$$

is an $\{\mathcal{F}_t\}$ submartingale

- **Definition (Quadratic Variation):** Fix $t > 0$ and let $\Pi = \{t_0, t_1, \dots, t_m\}$ with $0 = t_0 \leq t_1 \leq \dots \leq t_m = t$. Then, the p^{th} variation of X over Π is

$$V_t^{(p)}(\Pi) = \sum_{k=1}^m |X_{t_k} - X_{t_{k-1}}|^p.$$

Let the mesh of Π , denoted $\|\Pi\| = \max_{1 \leq k \leq m} |t_k - t_{k-1}|$. Then, if $V_t^{(2)}(\Pi)$ converges, in some sense, as $\|\Pi\| \rightarrow 0$, then the limit is the quadratic variation. If $X \in \mathcal{M}_2^c$ we have that

$$\lim_{\|\Pi\| \rightarrow 0} V_t^{(2)}(\Pi) \xrightarrow{P} \langle X \rangle_t.$$

- Moreover, if $\{X_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ is **continuous** and such that, for each fixed t , and some p

$$\lim_{\|\Pi\| \rightarrow 0} V_t^{(p)}(\Pi) \xrightarrow{P} L_t$$

where L_t is a random variable taking values in $[0, \infty)$, then

- $q > p \rightarrow \lim_{\|\Pi\| \rightarrow 0} V_t^{(q)}(\Pi) \xrightarrow{P} 0,$
- $q < p \rightarrow \lim_{\|\Pi\| \rightarrow 0} V_t^{(q)}(\Pi) \xrightarrow{P} \infty,$ on the event $\{L_t > 0\}$

Brownian Motion

Definition 22 *A standard one dimensional Brownian Motion (BM) is a continuous adapted process $W = \{W_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ defined on some probability space (Ω, \mathcal{F}, P) with the properties that*

1. $W_0 = 0$
 2. For $0 \leq s < t$, $W_t - W_s$ is independent of \mathcal{F}_s .
 3. $W_t - W_s \sim N(0, t - s)$
- Is this definition restrictive? Maybe. Consider the following

- **Result (Levy):** If $X \in \mathcal{M}^c$ (continuous path martingale) and X is such that its quadratic variation $\langle X \rangle_t = t$ as, for all intervals $[0, t]$, then X is a Brownian Motion.
- **Result (Breiman/Harrison):** If X is continuous (i.e. has continuous sample paths) and X has identical independent increments, then X is a Brownian Motion.
- Does a Brownian Motion exist? Yes.

Constructing a Brownian Motion

- Random walk interpretation of a BM. Consider a random walk Z_t such that

$$\Delta Z = Z_{j+1}^h - Z_j^h = \begin{cases} \Delta h & \text{with probability } p \\ -\Delta h & \text{with probability } 1 - p. \end{cases}$$

It follows that

$$\begin{aligned} E[Z_{j+1}^h - Z_j^h] &= \Delta h(2p - 1), \\ \text{Var}[Z_{j+1}^h - Z_j^h] &= 4p(1 - p)(\Delta h)^2. \end{aligned}$$

- Time interval of length T , and let $T = n\Delta t$.

- The cumulative change in $Z_{j+1}^h - Z_j^h$ over the whole interval is

$$\Delta_T Z = \underbrace{\Delta Z_1 + \dots + \Delta Z_n}_{n \text{ times}}$$

- It follows that

$$E[\Delta_T Z] = n\Delta h(2p - 1) = T \frac{\Delta h}{\Delta t} (2p - 1),$$
$$\text{Var}[\Delta_T Z] = n4(1 - p)\Delta h^2 = T \frac{\Delta h^2}{\Delta t} 4p(1 - p).$$

- Pick parameters (p and Δh) so that:

- mean is μT ,

- variance is $\sigma^2 T$

$$T \frac{\Delta h}{\Delta t} (2p - 1) = \mu T$$
$$T \frac{\Delta h^2}{\Delta t} 4p(1 - p) = \sigma^2 T.$$

or,

$$\Delta h = \frac{\mu \Delta t}{2p - 1}$$
$$(\Delta h)^2 = \left(\frac{\sigma^2 \Delta t}{4p(1 - p)} \right)^{1/2}.$$

- The solution is

$$\Delta h = \sigma \sqrt{\Delta t} \left[\sqrt{1 + \left(\frac{\mu}{\sigma}\right) \Delta t} \right],$$
$$p_i = \frac{1}{2} \left\{ 1 \pm \left(\frac{\mu}{\sigma}\right) \frac{\sqrt{\Delta t}}{\sqrt{1 + \left(\frac{\mu}{\sigma}\right) \Delta t}} \right\}.$$

- Since this is an approximation that is valid when $\Delta t \rightarrow 0$, the solution can be described as

$$\Delta h = \sigma \sqrt{\Delta t},$$
$$p_i = \frac{1}{2} \left\{ 1 \pm \left(\frac{\mu}{\sigma}\right) \frac{\sqrt{\Delta t}}{\sqrt{1 + \left(\frac{\mu}{\sigma}\right) \Delta t}} \right\}.$$

- Special Case: Wiener process or standard Brownian motion (SBM), we have $\mu = 0$ and $\sigma = 1$.

$$\begin{aligned}\Delta h &= \sigma\sqrt{\Delta t}, \\ p_i &= \frac{1}{2}.\end{aligned}$$

- Thus, one way of thinking about Brownian Motion is as the sum of a sequence of Bernoulli *i.i.d.* random variables, with the size of the jump of the order of the square root of dt
- What is the *quadratic variation* of this process?

$$\langle \Delta Z \rangle = \sum_{j=1}^n \underbrace{[\Delta Z_j]_{\Delta h}}^2 = \sum_{j=1}^n [\sqrt{\Delta t}]^2 = n\Delta t = T.$$

- Random walk has the property that its quadratic variation is t in any interval of length t .

- Another derivation of a Brownian Motion.
- Intuition: Sum of white noise “scaled” by \sqrt{dt}
- Consider the difference between a $Z(T + s)$ and $Z(s)$. The length of this interval is T . Partition this interval into n equally spaced segments of length Δt . Thus, $T = n\Delta t$. Let's define

$$Z(T + s) - Z(s) = \sum_{i=1}^n \varepsilon_i \sqrt{\Delta t},$$

where ε_i is a collection of independent random variables, each distributed $N(0, 1)$. It follows that

$$\begin{aligned} E[Z(T + s) - Z(s)] &= 0, \\ \text{var}[Z(T + s) - Z(s)] &= n\Delta t = T. \end{aligned}$$

- Given the properties of the normal distribution,

$$Z(T + s) - Z(s) \sim N(0, T).$$

- “Push” the notation and define

$$dZ_t = Z(t + dt) - Z(t),$$

then,

$$dZ_t \approx \varepsilon_t \sqrt{dt},$$

from which it follows that

$$\begin{aligned} E[dZ_t] &= 0, \\ \text{var}[dZ_t] &= dt. \end{aligned}$$

- If Z_t^1 and Z_t^2 are two standard Brownian Motion, then

$$E[dZ_t^1 dZ_t^2] \approx \varepsilon_t^1 \varepsilon_t^2 dt = \rho_{12} dt,$$

where ρ_{12} is the correlation coefficient between the two normal random variables.

- Let's consider now a (μ, σ) Brownian Motion. given by,

$$X_t = X_0 + \mu t + \sigma Z_t.$$

It follows that

$$X_{t+k} = X_t + \mu k + \sigma(Z_{t+k} - Z_t).$$

- Then, the best predictor of X_{t+k} given X_t is

$$E[X_{t+k} | X_t] = X_t + \mu k,$$

while the one standard deviation bands around this estimate are:

$$X_t + \mu k \pm \sigma \sqrt{k}.$$

Remark 23 *What dominates the behavior of the best estimate, μ or σ ? Since $X_{t+k} - X_t$ has mean μk and standard deviation $\sigma \sqrt{k}$, then*

$$\frac{\mu k}{\sigma \sqrt{k}} \rightarrow \infty \text{ as } k \rightarrow \infty, \quad [\text{mean dominates}]$$

while

$$\frac{\mu k}{\sigma \sqrt{k}} \rightarrow 0 \text{ as } k \rightarrow 0, \quad [\text{standard deviation dominates}]$$

- What do we know about Brownian Motion? There are a number of results that hold for all martingales (and some for martingales with continuous paths) that directly apply to a Brownian Motion.

Claim 24 *Let $W = \{W_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ be a Brownian Motion then,*

1. *W is a Markov process.*
2. *W is a martingale.*
3. *$\langle W \rangle_t = t$ [Quadratic Variation]*

Proof. Using the definition of quadratic variation

$$\langle W \rangle_t \equiv \lim_{n \rightarrow \infty} \sum_{i=1}^{2^n - 1} [W_{t_{i+1}^n} - W_{t_i^n}]^2,$$

where

$$t_i^n = \frac{it}{2^n}, \quad i = 0, 1, \dots, 2^n.$$

Since $W_{t_{i+1}^n} - W_{t_i^n} \sim N(0, t_{i+1}^n - t_i^n) = N(0, \frac{t}{2^n})$, it follows that

$$Z_i \equiv \sqrt{2^n} [W_{t_{i+1}^n} - W_{t_i^n}] \sim N(0, t).$$

Thus,

$$\sum_{i=1}^{2^n - 1} [W_{t_{i+1}^n} - W_{t_i^n}]^2 = \langle W \rangle_t \equiv \sum_{i=1}^{2^n - 1} \frac{1}{2^n} Z_i^2.$$

By the law of large numbers this term converges (a.s.) to $E[Z_i^2] = t$ ■

4. $W^2 - \langle W \rangle_t$ is a martingale

Claim 25 *If a function is differentiable (with bounded derivative) then its quadratic variation is zero*

Proof. *Let $f(t)$ be a function. Then, given a partition $\Pi = \{0 = t_0 < t_1 < \dots < t_n = t\}$, the mean Value Theorem implies that*

$$f(t_{i+1}) - f(t_i) = f'(\tau_i)(t_{i+1} - t_i).$$

The quadratic variation satisfies

$$\begin{aligned} \left| \sum_{i=1}^n [f(t_{i+1}) - f(t_i)]^2 \right| &= \left| \sum_{i=1}^n [f'(\tau_i)(t_{i+1} - t_i)]^2 \right| \\ &\leq \max |f'(\tau)| \sum_{i=1}^n (t_{i+1} - t_i)^2 \\ &\leq \max_i |f'(\tau_i)| \max_i (t_{i+1} - t_i)t. \end{aligned}$$

However, as the mesh of the partition goes to 0, $\max(t_{i+1} - t_i) \rightarrow 0$ and, hence, the quadratic variation is zero. ■

Claim 26 Let $W = \{W_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ be a Brownian Motion then its total variation is ∞

Proof. Let $\Pi = \{0 = t_0 < t_1 < \dots < t_n = t\}$ be a partition of the interval $[0, t]$. Then,

$$\sum_{i=1}^n [W_{t_{i+1}} - W_{t_i}]^2 \leq \max_i (W_{t_{i+1}} - W_{t_i}) \sum_{i=1}^n |W_{t_{i+1}} - W_{t_i}|.$$

$\max_i (W_{t_{i+1}} - W_{t_i}) \rightarrow 0$ (by continuity). Since $\langle W \rangle_t = \sum_{i=1}^n [W_{t_{i+1}} - W_{t_i}]^2 = t$ is positive (and finite), it follows that the term $\sum_{i=1}^n |W_{t_{i+1}} - W_{t_i}|$ must converge to ∞ ■

Starting from the standard BM we can create what we will denote a (μ, σ) -BM.

This is a process X_t given by

$$X_t(\omega) = X_0 + \mu t + \sigma W_t(\omega).$$

In the following claims the X_t process is the one given above.

Claim 27 *The process $X_t(\omega) = X_0 + \mu t + \sigma W_t(\omega)$ is a submartingale (supermartingale) if $\mu \geq (\leq) 0$.*

Claim 28 $Y_t \equiv X_t - \mu t$ is a martingale,

Claim 29 $\langle Y \rangle_t = \sigma^2 t$.

Claim 30 $Y_t^2 - \sigma^2 t$ is a martingale.

Claim 31 $\left(\frac{Y_t}{\sigma}\right)^2 - t$ is a martingale.

Claim 32 (Wald Martingale) Let $Z_t \equiv e^{[\beta X_t - q(\beta)t]}$, with $q(\beta) \equiv \beta\mu + \frac{1}{2}\beta^2\sigma^2$. Then, Z_t is a martingale.

Proof. To see this, note that

$$e^{[\beta X_t - q(\beta)t]} = e^{[\beta(X_t - X_s) - q(\beta)(t-s)]} e^{[\beta X_s - q(\beta)s]}.$$

Taking expectations conditional on $\{\mathcal{F}_s\}$ on both sides we get

$$E[Z_t | \mathcal{F}_s] = Z_s E[e^{[\beta(X_t - X_s) - q(\beta)(t-s)]} | \mathcal{F}_s].$$

Thus, it suffices to show that

$$E[e^{[\beta(X_t - X_s) - q(\beta)(t-s)]} | \mathcal{F}_s] = 1.$$

However, $\beta(X_t - X_s) \sim N(\beta\mu(t-s), \beta^2\sigma^2(t-s))$, and the expectation of any such log-normal random variable is

$$E[e^{\beta(X_t - X_s)} | \mathcal{F}_s] = e^{\beta\mu(t-s) + \frac{1}{2}\beta^2\sigma^2(t-s)} = e^{q(\beta)(t-s)},$$

which completes the proof ■

Claim 33 $(X_t - \mu t)^2 - \sigma^2 t$ is a martingale

- An important property of Brownian Motion is that it is a Strong Markov process.

Definition 34 (Strong Markov) *A process X with initial distribution λ (and associated probability measure P^λ) is said to be a strong Markov process if*

1. $P^\lambda[X_0 \in \Gamma] = \mu(\Gamma)$, for all $\Gamma \in \mathcal{B}(\mathbb{R}^d)$

2. For any optional time S , $t \geq 0$ and $\Gamma \in \mathcal{B}(\mathbb{R}^d)$

$$P^\lambda[X_{S+t} \in \Gamma \mid \mathcal{F}_{S+}] = P^\lambda[X_{S+t} \in \Gamma \mid X_S],$$

P^λ – as on $\{S < \infty\}$

- There is another way of describing the strong Markov property which reveals more clearly its implications.
- Let $W = \{W_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ be a Brownian Motion and let S be a stopping time of the filtration $\{\mathcal{F}_t\}$. Let

$$W_t^* \equiv W_{S+t} - W_S.$$

- Then

1. W_t^* is a Brownian motion.
2. W_t^* is independent of S .

- *Implication* of the strong Markov property. Let T be an arbitrary stopping time. Define the random variable Z_t^* by

$$Z_t^*(\omega) \equiv W_{T(\omega)+t}(\omega), \quad t \geq 0, \quad \text{on } \{\omega : T(\omega) < \infty\}.$$

- Note that the process Z_t^* need not be defined at all on the set $\{\omega : T(\omega) = \infty\}$.

- Let the function F be a measurable mapping such that

$$E^x[|F(Z)|] < \infty, \quad \forall x \in \mathfrak{R}.$$

- Strong Markov property implies that

$$E^x[F(Z_t^*) | \mathcal{F}_T] = F(Z_0^*) = F(W_T), \quad \text{on } \{\omega : T(\omega) < \infty\}.$$

- This result comes in handy when one needs to compute functions of a stopped BM.

The Reflection Principle

- Let $W = \{W_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ be a standard BM, and let

$$T_b(\omega) \equiv \inf\{t \geq 0 : W_t(\omega) = b\}.$$

It follows that T_b is a stopping time of the filtration $\{\mathcal{F}_t\}$.

Proposition 35 $P^0[T_b < t] = 2P^0[W_t > b] = \frac{2}{\sqrt{2\pi}} \int_{bt^{-1/2}}^{\infty} e^{-\frac{x^2}{2}} dx$

Proof. (*sketch*)

1. First claim that $P^0[T_b < t] = P^0[T_b < t, W_t > b] + P^0[T_b < t, W_t < b]$.

2. The set $\{T_b < t, W_t > b\} = \{W_t > b\}$. Why? If $W_t > b$ it must be the case that $T_b < t$, as $W_0 = 0$. Thus, the extra conditioning does not change the set. What about the other set, $\{T_b < t, W_t < b\}$? On this set, the Brownian motion hit b at some point, and then drifted to a point $c < b$. Given that the distribution of a Brownian motion is symmetric (because the Normal is a symmetric distribution), the probability of traveling down a distance $b - c$ is the same as the probability of traveling up the same distance. Thus,

$$P^0[T_b < t, W_t < b] = P^0[T_b < t, W_t > b].$$

Thus,

$$\begin{aligned} P^0[T_b < t] &= 2P^0[T_b < t, W_t > b] = 2P^0[W_t > b] \\ &= \frac{2}{\sqrt{2\pi}} \int_{bt^{-1/2}}^{\infty} e^{-\frac{x^2}{2}} dx \end{aligned}$$



- The above proof is somewhat heuristic (but close to being right) but it relies heavily on the idea that a Brownian motion has the strong Markov property. Where was this used? We basically used to argue that the process

$$W_{T_b+t} - W_{T_b}$$

is a Brownian motion that is independent of \mathcal{F}_{T_b} , the σ -field of events determined prior to T_b . Of course, to claim the strong Markov property, T_b has to be a stopping time as we showed (it is a hitting time).

- Here is another application of the strong Markov property

Proposition 36 *Let $W = \{W_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ be a standard BM, with $X_0 = 0$. Let*

$$M_t \equiv \sup\{W_s, 0 \leq s \leq t\},$$

then

$$P^0[W_t \leq x, M_t \leq y] = \Phi\left(\frac{x}{\sqrt{t}}\right) - \Phi\left(\frac{x - 2y}{\sqrt{t}}\right)$$

where Φ is the cdf of a standard normal random variable, i.e. a $N(0, 1)$

Proof.

1. Note that

$$P^0[W_t \leq x, M_t \leq y] = P^0[W_t \leq x] - P^0[W_t \leq x, M_t > y].$$

2. First term is

$$P^0[W_t \leq x] = \Phi\left(\frac{x}{\sqrt{t}}\right)$$

given that W_t is an $N(0, t)$ random variable.

3. $P^0[W_t \leq x, M_t > y]$? This event corresponds to the case in which the process W_t hit the value y , and then traveled to a point below x .
4. Conditional on being at y , traveling down below x (a distance $y - x$) has the same probability (given symmetry of the Normal distribution) of traveling up a distance $y - x$.
5. Let T be the first time that the process W_t hits y . Then, define $W_{t-T}^* \equiv W_t - W_T = W_t - y$.
6. Need to compute the probability of W_{t-T}^* increasing by at least $(y - x)$.

7. This is the probability of the event $\{W_{t-T}^* \geq y - x\} = \{W_t \geq 2y - x\} = \{W_t \leq x - 2y\} = \Phi\left(\frac{x-2y}{\sqrt{t}}\right)$.

$$\begin{aligned} P^0[W_t \leq x, M_t > y] &= P^0[T < t, W_{t-T}^* > y - x] \\ &= P^0[T < t, W_{t-T}^* > y - x] = P^0[W_t \leq x - 2y] = \Phi\left(\frac{x - 2y}{\sqrt{t}}\right). \end{aligned}$$

Thus, putting together these two pieces we get the desired result.



Some Results

- Assume that $W = \{W_t, \{\mathcal{F}_t\}, 0 \leq t < \infty\}$ is a standard BM. Start the process at $W_0 = x$ (use P^x on (Ω, \mathcal{F})).
- Let

$$T_b(\omega) \equiv \inf\{t \geq 0 : W_t(\omega) = b\}$$

and

$$M_t \equiv \sup\{W_s, 0 \leq s \leq t\}.$$

Proposition 37 For $t > 0$ and $a \leq b, b > 0$

$$P^0[W_t \in da, M_t \in db] = \frac{2(2b - a)}{\sqrt{2\pi t^3}} e^{-\frac{(2b-a)^2}{2t}} da db.$$

Proof. See previous results. ■

Proposition 38 Let $t > 0, b > 0$

$$1. P^0[M_t \in db] = P^0[| W_t | \in db] = P^0[M_t - W_t \in db] = \frac{2}{\sqrt{2\pi t}} e^{-\frac{b^2}{2t}} db.$$

$$2. P^0[\max_{0 \leq u \leq t} | W_u | \geq b] \leq 4P^0[W_t \geq b] \leq \sqrt{\frac{t}{2\pi}} \frac{4}{b} e^{-\frac{b^2}{2t}}.$$

3. $1 \rightarrow P^0[T_b \leq t] = P^0[M_t \geq b]$ with density

$$P^0[T_b \in dt] = \frac{b}{\sqrt{2\pi t^3}} e^{-\frac{b^2}{2t}} dt,$$

has Laplace transform

$$E^0[e^{-\alpha T_b}] = e^{-b\sqrt{\alpha}}.$$

Proof. (of the Laplace transform result) Define the martingale

$$X_t = e^{\lambda W_t - \frac{1}{2}\lambda^2 t}.$$

Since, $W_{T_b} = b$ as and $X_0 = 1$. Then, the OST theorem implies

$$\begin{aligned} E^0[X_{T_b}] &= E^0[X_0] = 1, \\ E^0[e^{\lambda b - \frac{1}{2}\lambda^2 T_b}] &= 1, \\ E^0[e^{-\frac{1}{2}\lambda^2 T_b}] &= e^{-\lambda b}, \end{aligned}$$

then, setting $\lambda = \sqrt{2\alpha}$, the result follows. ■

Claim 39 $\lim_{t \rightarrow \infty} P^0[T_b \leq t] = 1$ but $E^0[T_b] = \infty$.

Proof. To see this, use the formula

$$P^0[T_b \in dt] = \frac{b}{\sqrt{2\pi t^3}} e^{-\frac{b^2}{2t}} dt,$$

to compute

$$P^0[T_b \leq t] = \int_0^t \frac{b}{\sqrt{2\pi s^3}} e^{-\frac{b^2}{2s}} ds.$$

It is convenient to use the change of variable formula $z = \frac{b}{\sqrt{s}}$. Note that

$$dz = -\frac{1}{2b^2} \frac{b}{\sqrt{s}} \frac{b^2}{s} ds = -\frac{1}{2b^2} z^3 ds$$

or,

$$ds = -\frac{2b^2}{z^3} dz.$$

Using the same change of variables in the integral, it follows that

$$\begin{aligned} \int_0^t \frac{b}{\sqrt{2\pi s^3}} e^{-\frac{b^2}{2s}} ds &= \int_{\frac{b}{\sqrt{t}}}^{\infty} -\frac{2}{\sqrt{2\pi}} z^3 e^{-\frac{1}{2}z^2} \frac{1}{z^3} dz = 2 \int_{\frac{b}{\sqrt{t}}}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}z^2} dz \\ &= 2[1 - \Phi(\frac{b}{\sqrt{t}})] \end{aligned}$$

where, as before, $\Phi(x)$ is the cdf of a standard normal random variable. Thus,

$$P^0[T_b \leq t] = 2[1 - \Phi(\frac{b}{\sqrt{t}})] \xrightarrow{t \rightarrow \infty} 1.$$

Now, to show that $E^0[T_b] = \infty$ we use a similar computation. Note that

$$E^0[T_b] = \int_0^{\infty} \frac{bs}{\sqrt{2\pi s^3}} e^{-\frac{b^2}{2s}} ds.$$

Thus, using the same change of variables as before, we get

$$E^0[T_b] = 2 \int_0^{\infty} \frac{1}{\sqrt{2\pi}} z e^{-\frac{1}{2}z^2} \frac{1}{z^3} dz = 2 \int_0^{\infty} \frac{1}{\sqrt{2\pi}} \frac{1}{z^2} e^{-\frac{1}{2}z^2} dz.$$

However, this is just the expectation of $1/X^2$ where $X \sim N(0, 1)$. It is a standard result that this expectation is infinite (or just compute the integral)



Claim 40 *Let T be defined by (for $a, b > 0$)*

$$T = \inf\{t : W_t = -a, \text{ or } W_t = b\}$$

then show that $E^0[T] < \infty$

1. **Proof.** *To see this, let*

$$T_n \equiv \min\{T, n\}.$$

Since the stopping times T_n are bounded, the OST theorem can be applied.

Since, as we showed before, the process

$$Z_t = W_t^2 - t$$

is a martingale, the OST theorem implies that

$$E^0[Z_{T_n}] = E^0[Z_0] = 0,$$

However, $W_{T_n}^2 \leq \min\{a, b\}$. Thus,

$$0 = E^0[Z_{T_n}] = E^0[W_{T_n}^2 - T_n] \leq \min\{a, b\} - E^0[T_n].$$

It follows that

$$E^0[T_n] \leq \min\{a, b\}.$$

But now the sequence $\{T_n\}$ is converging to T , and is bounded below by 0. Thus, the monotone convergence theorem (version I with $Y = 0$) implies the desired result.

Remark 41 Note that in the previous case, when the stopping time is T_b , this bound does not bind (of course, since, in that case we have to take $a \rightarrow \infty$).

■