

Unit Roots

- An autoregressive process

$$a(L)y_t = e_t$$

has a unit root if

$$a(1) = 0$$

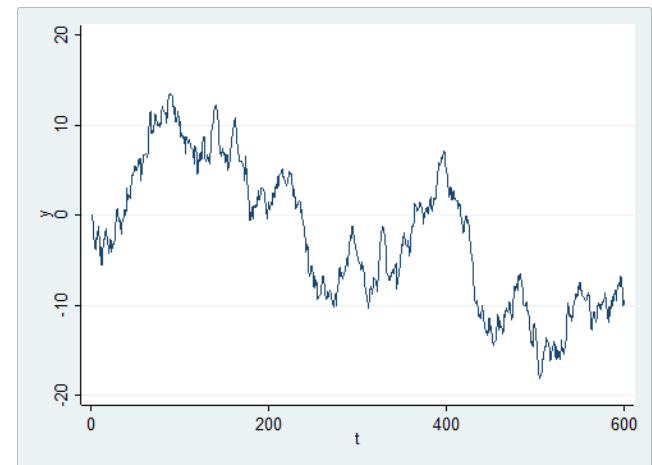
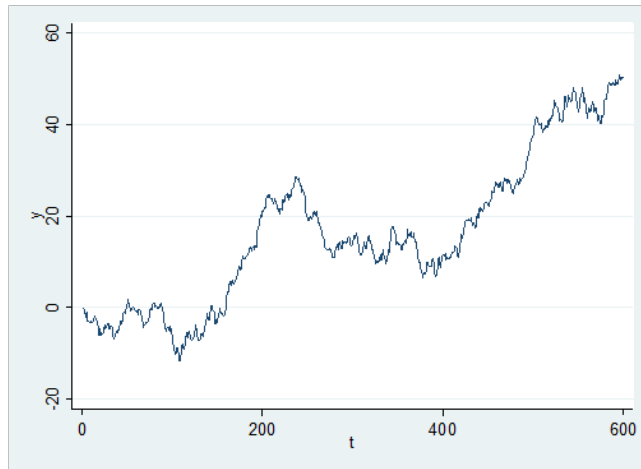
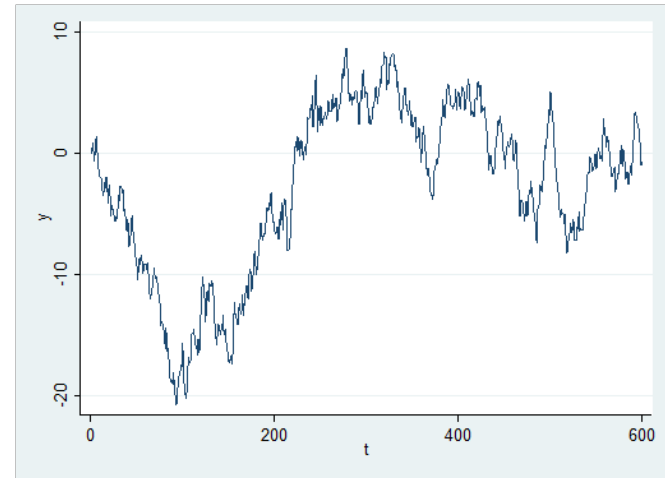
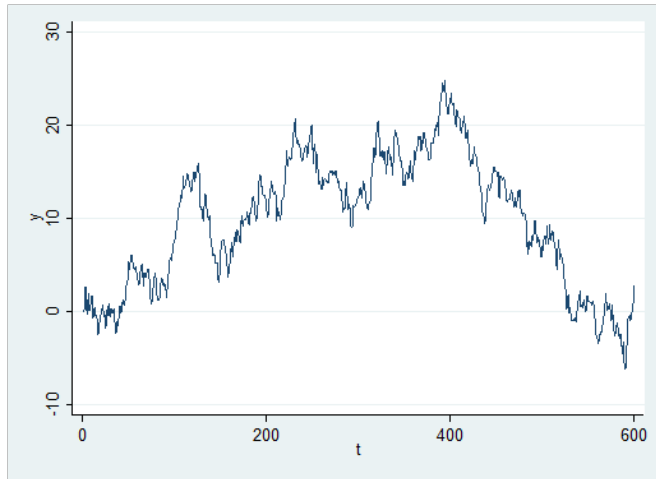
- The simplest case is the AR(1) model

$$(1 - L)y_t = e_t$$

or

$$y_t = y_{t-1} + e_t$$

Examples of Random Walks



Random Walk with Drift

- AR(1) with non-zero intercept and unit root

$$y_t = \alpha + y_{t-1} + e_t$$

- This is same as Trend plus random walk

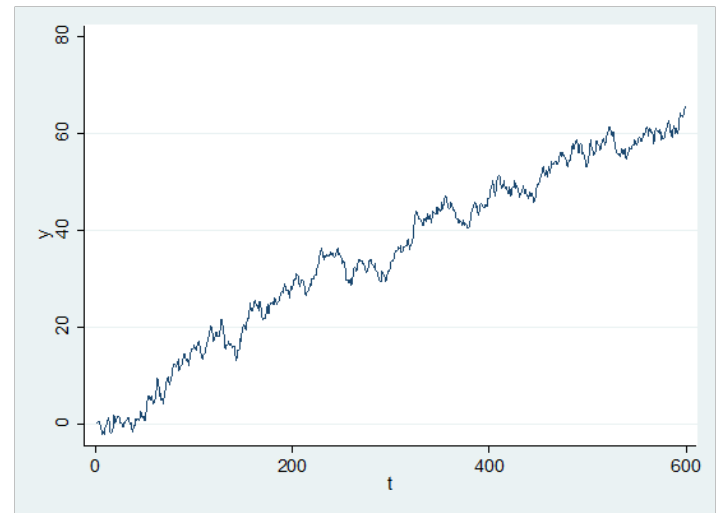
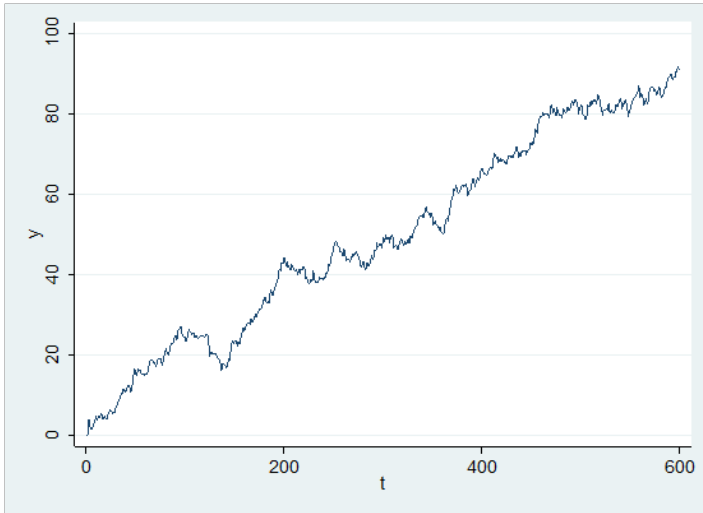
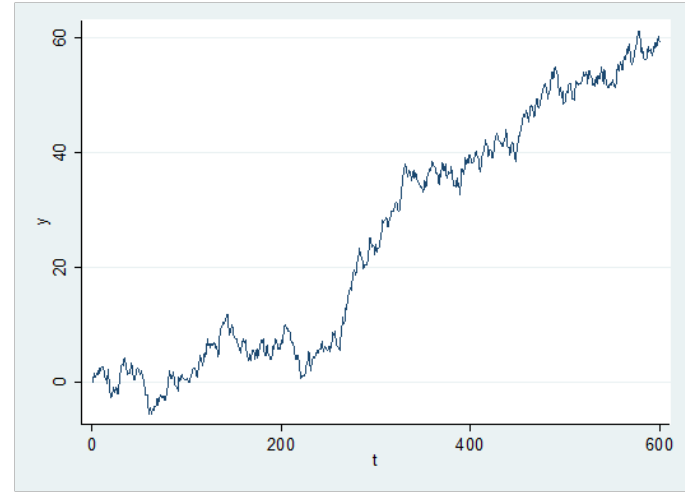
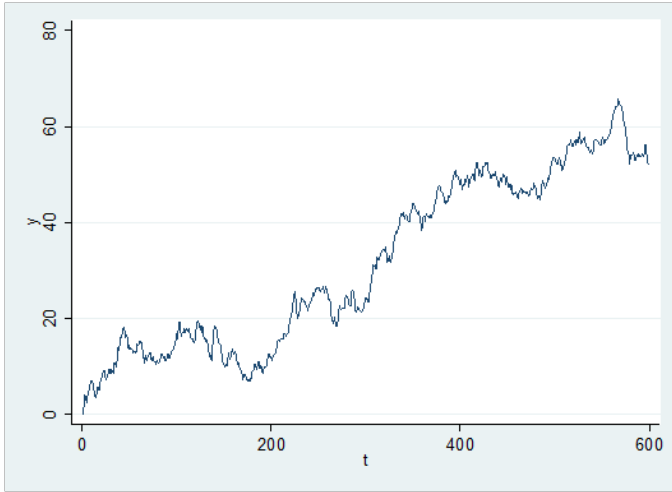
$$y_t = T_t + C_t$$

$$T_t = \alpha t$$

$$C_t = C_{t-1} + e_t$$

Examples

$$y_t = 0.1 + y_{t-1} + e_t$$
$$e_t \sim N(0,1)$$



Optimal Forecasts in Levels

- Random Walk

$$y_{t+1|t} = y_t$$

$$y_{t+h|t} = y_t$$

- Random Walk with drift

$$y_{t+h|t} = \alpha + y_t$$

$$y_{t+h|t} = \alpha h + y_t$$

Optimal Forecasts in Changes

- Take differences (growth rates if y in logs)

$$z_t = \Delta y_t = y_t - y_{t-1}$$

- Optimal forecast: Random walk

$$z_{t+h|t} = 0$$

- Optimal forecast: Random walk with drift

$$z_{t+h|t} = \alpha h$$

Forecast Errors

- By back-substitution

$$y_t = y_{t-1} + e_t$$

$$= y_{t-h} + e_{t-h+1} + \dots + e_{t+1}$$

- So the forecast error from an h-step forecast is

$$e_{t-h+1} + \dots + e_{t+1}$$

- Which has variance

$$\sigma^2 + \dots + \sigma^2 = h\sigma^2$$

- Thus the forecast variance is linear in h

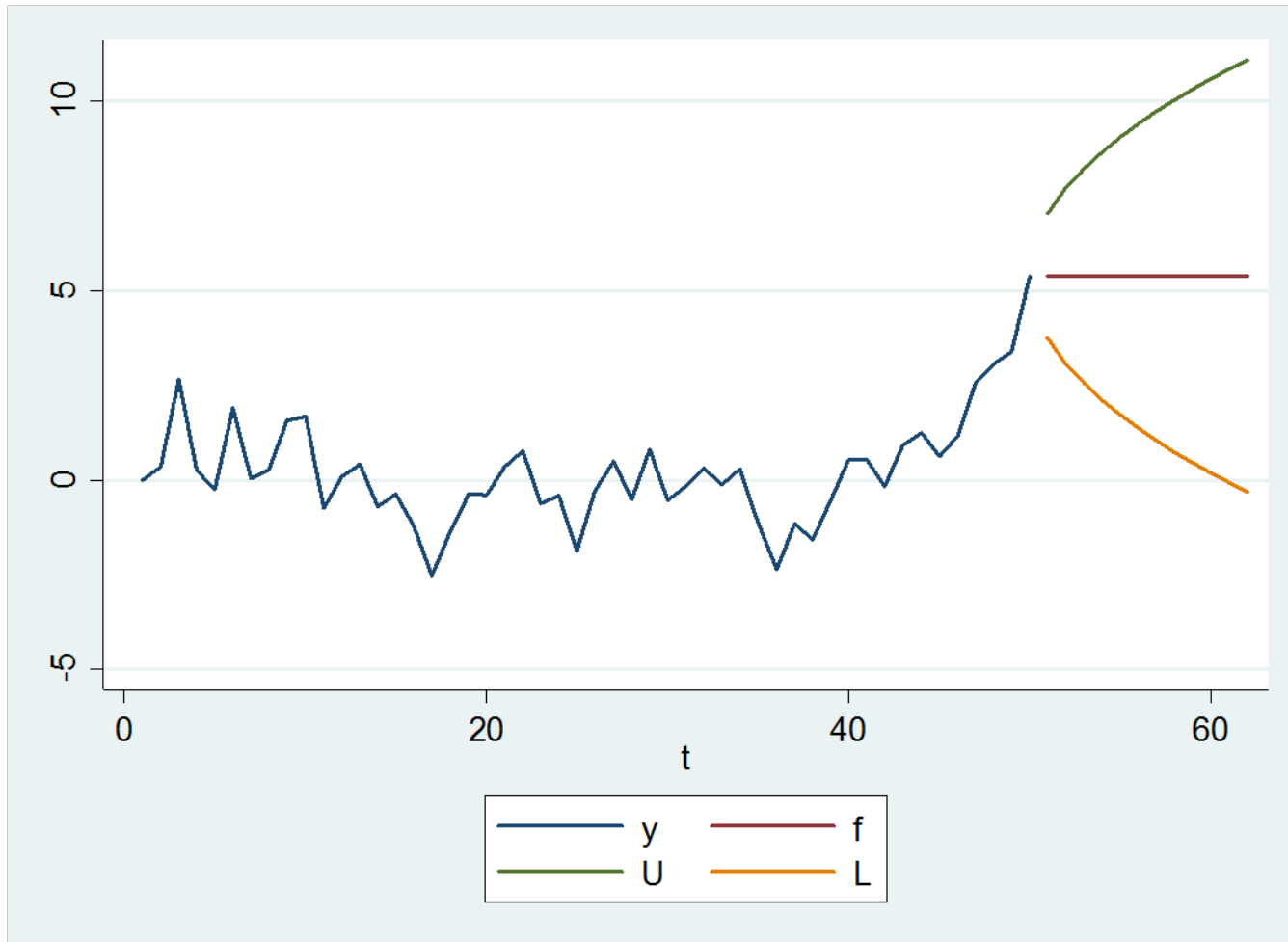
Forecast intervals

- The forecast intervals are proportional to the forecast standard deviation

$$\sqrt{h\sigma^2} = \sqrt{h}\sigma$$

- Thus the forecast intervals fan out with the square root of the forecast horizon h

Example: Random Walk



General Case

- If y has a unit root, transform by differencing

$$z_t = \Delta y_t = y_t - y_{t-1}$$

- This eliminates the unit root, so z is stationary.

$$a(L)y_t = e_t$$

$$a(L) = b(L)(1 - L)$$

$$b(L)z_t = e_t$$

- Make forecasts of z
 - Forecast growth rates instead of levels

Forecasting levels from growth rates

- If you have a forecast for a growth rate, you also have a forecast for the level
- If the current level is 253, and the forecasted growth is 2.3%, the forecasted level is 259
- If a 90% forecast interval for the growth is [1%, 4%], the 90% interval for the level is [256,263]

Estimation with Unit Roots

- If a series has a unit root, it is non-stationary, so the mean and variance are changing over time.
- Classical estimation theory does not apply
- However, least-squares estimation is still consistent

Consistent Estimation

- If the true process is

$$y_t = y_{t-1} + e_t$$

- And you estimate an AR(1)

$$y_t = \hat{\alpha} + \hat{\beta}y_{t-1} + \hat{e}_t$$

- Then the coefficient estimates will converge in probability to the true values (0 and 1) as T gets large

Example on simulated data

- N=50

| y | Coef. | Std. Err. | t | P> t | [95% Conf. Interval] | |
|---------------------|----------|-----------|-------|-------|----------------------|----------|
| ^y L1. | .9240092 | .0588153 | 15.71 | 0.000 | .805688 | 1.04233 |
| _cons | .0492537 | .1419531 | 0.35 | 0.730 | -.2363192 | .3348266 |

- N=200

| y | Coef. | Std. Err. | t | P> t | [95% Conf. Interval] | |
|---------------------|----------|-----------|-------|-------|----------------------|----------|
| ^y L1. | .9737057 | .0213262 | 45.66 | 0.000 | .9316487 | 1.015763 |
| _cons | .0987149 | .076367 | 1.29 | 0.198 | -.0518868 | .2493166 |

- N=400

| | | | | | | |
|---------------------|----------|----------|--------|-------|-----------|----------|
| ^y L1. | .9899704 | .0068761 | 143.97 | 0.000 | .9764523 | 1.003489 |
| _cons | .0605234 | .0596962 | 1.01 | 0.311 | -.0568368 | .1778837 |

Model with drift

- If the truth is

$$y_t = \alpha + y_{t-1} + e_t$$

- And you estimate an AR(1) with trend

$$y_t = \hat{\alpha} + \hat{\gamma}t + \hat{\beta}y_{t-1} + \hat{e}_t$$

- Then the coefficient estimates converge in probability to the true values $(\alpha, 0, 1)$
- It is important to include the time trend in this case.

Example with simulated data with drift

- N=50

| y | Coef. | Std. Err. | t | P> t | [95% Conf. Interva] | |
|------------------------|-----------------|------------------|--------------|-----------------|----------------------------|-----------------|
| t | .0230531 | .0159104 | 1.45 | 0.154 | -.0089728 | .055079 |
| y L1. | .8814838 | .0697116 | 12.64 | 0.000 | .7411615 | 1.021806 |
| _cons | .1336359 | .2670196 | 0.50 | 0.619 | -.4038467 | .6711185 |

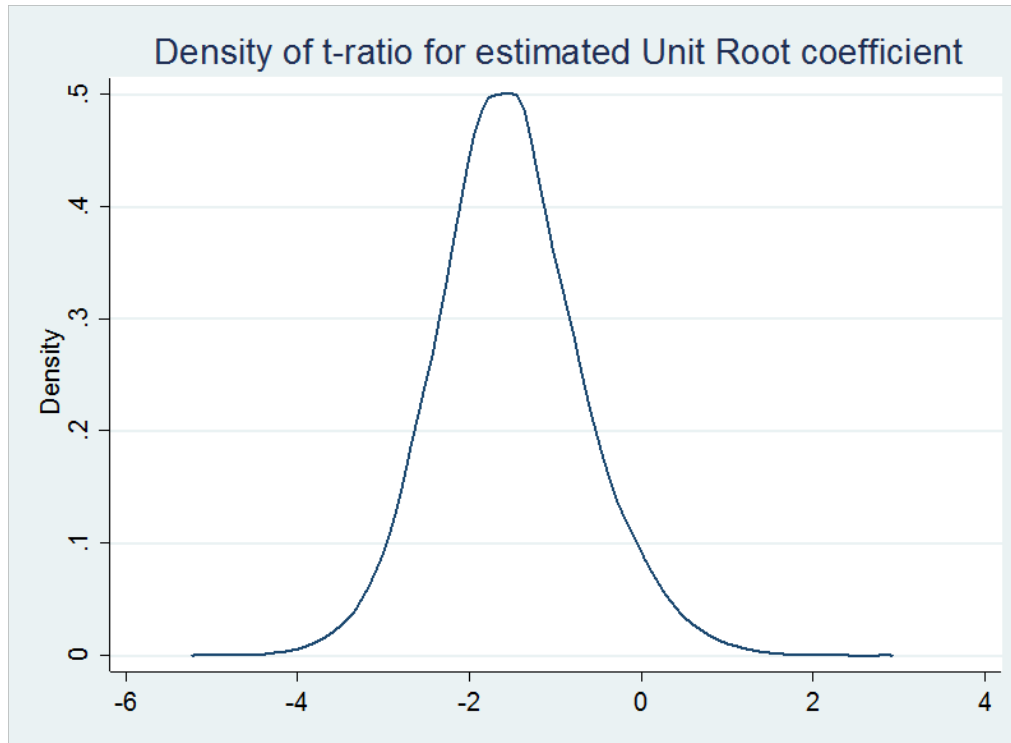
- N=200

| y | Coef. | Std. Err. | t | P> t | [95% Conf. Interva] | |
|------------------------|-----------------|------------------|--------------|-----------------|----------------------------|-----------------|
| t | .000763 | .0015264 | 0.50 | 0.618 | -.0022472 | .0037732 |
| y L1. | .9423076 | .0187133 | 50.36 | 0.000 | .9054024 | .9792129 |
| _cons | .944347 | .2474848 | 3.82 | 0.000 | .4562721 | 1.432422 |

Non-Standard Distribution

- A problem is that the sampling distribution of the least-squares estimates and t-ratios are not normal when there is a unit root
- Critical values quite different than conventional

Density of t-ratio



- Non-Normal
- Negative bias

Testing for a Unit Root

- Null hypothesis:
 - There is a unit root
- In AR(1)
 - Coefficient on lagged variable is “1”
- In AR(k)
 - Sum of coefficients is “1”

AR(1) Model

- Estimate

$$y_t = \hat{\alpha} + \hat{\beta}y_{t-1} + \hat{e}_t$$

- Or equivalently

$$\Delta y_t = \hat{\alpha} + \hat{\rho}y_{t-1} + \hat{e}_t$$

$$\hat{\rho} = \hat{\beta} - 1$$

- Test for $\beta=1$ same as test for $\rho=0$.
- Test statistic is t-ratio on lagged y

AR(k+1) model

- Estimate

$$\Delta y_t = \hat{\alpha} + \hat{\rho}y_{t-1} + \hat{\beta}_1\Delta y_{t-1} + \cdots + \hat{\beta}_k\Delta y_{t-k} + \hat{e}_t$$

- Test for $\rho=0$
- Called ADF test
 - Augmented Dickey-Fuller
 - (Test without extra lags is called Dickey-Fuller, test with extra lags called Augmented Dickey-Fuller)

Theory of Unit Root Testing

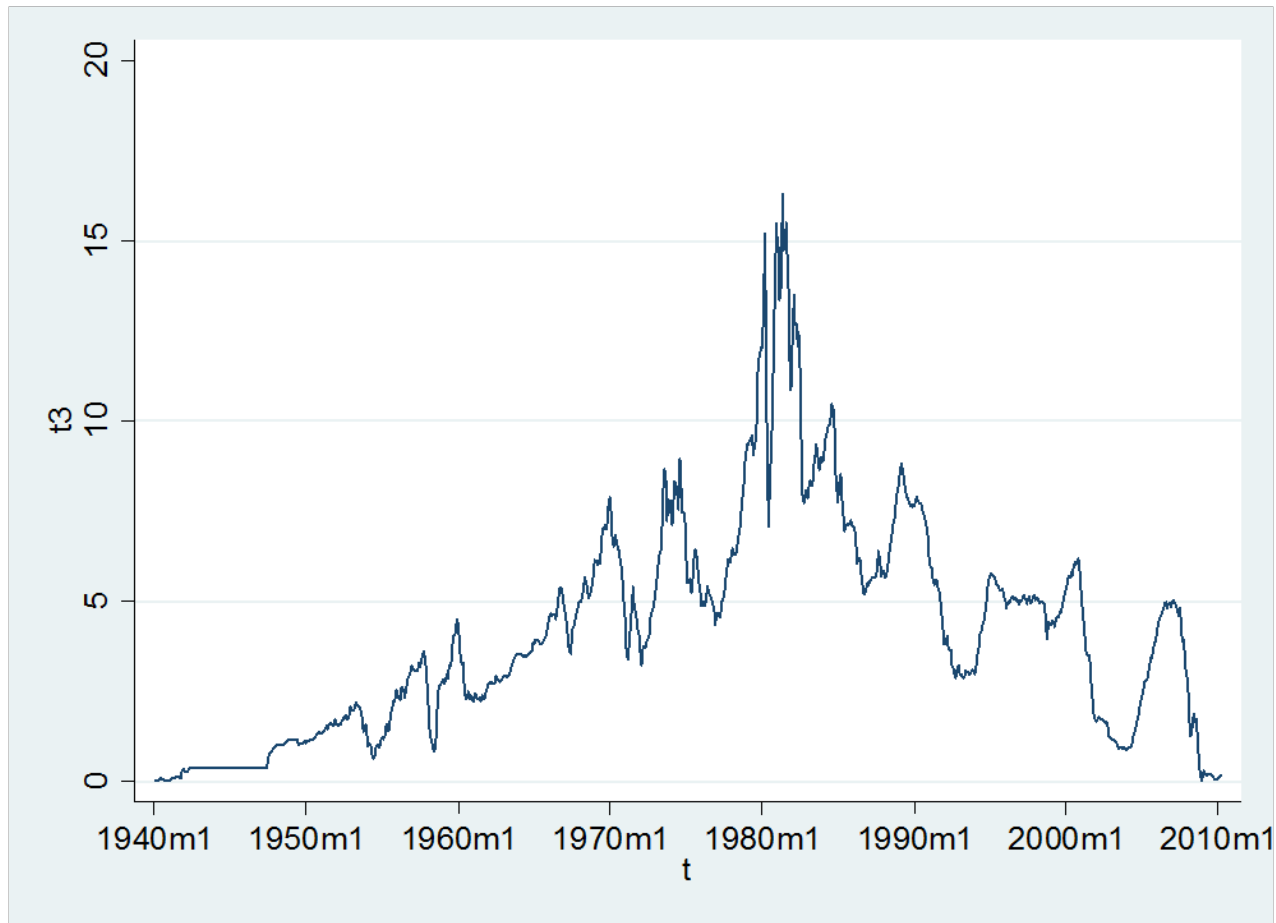
- Wayne Fuller (Iowa State)
 - David Dickey (NCSU)
 - Developed DF and ADF test
- Peter Phillips (Yale)
 - Extended the distribution theory



STATA ADF test

- **dfuller t3, lags(12)**
- This implements a ADF test with 12 lags of differenced data
- Equivalent to an AR(13)
- Alternatively
- **reg d.t3 L.t3 L(1/12).d.t3**

Example: 3-month T-bill



Example: 3-month T-bill

```
. dfuller t3, lags(12)
```

Augmented Dickey-Fuller test for unit root Number of obs = 902

| | Test Statistic | Interpolated Dickey-Fuller | | |
|------|-------------------|----------------------------|----------------------|-----------------------|
| | | 1% Critical Value | 5% Critical Value | 10% Critical Value |
| z(t) | -2.004 | -3.430 | -2.860 | -2.570 |

MacKinnon approximate p-value for z(t) = 0.2849

- The p-value is not significant
- Equivalently, the statistic of -2 is not smaller than the 10% critical value
- Do not reject a unit root for 3-month T-Bill

Alternatively

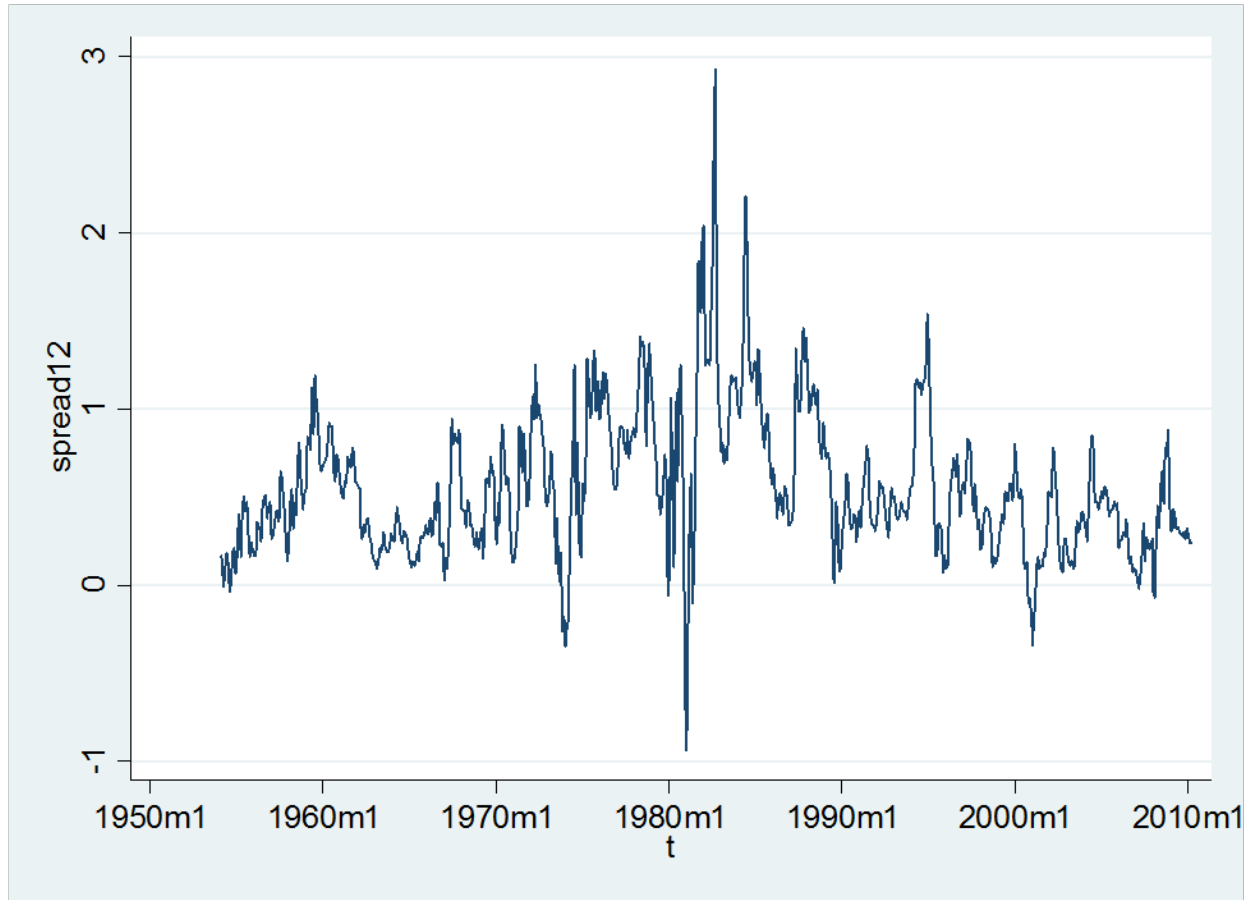
. reg d.t3 L.t3 L(1/12).d.t3

| Source | SS | df | MS | | | |
|----------|------------|-----|------------|-----------------|--------|--|
| Model | 33.1413569 | 13 | 2.54933515 | Number of obs = | 902 | |
| Residual | 100.553334 | 888 | .113235736 | F(13, 888) = | 22.51 | |
| Total | 133.694691 | 901 | .148384784 | Prob > F = | 0.0000 | |
| | | | | R-squared = | 0.2479 | |
| | | | | Adj R-squared = | 0.2369 | |
| | | | | Root MSE = | .33651 | |

| d.t3 | Coef. | Std. Err. | t | P> t | [95% Conf. Interval] | |
|-------|-----------|-----------|-------|-------|----------------------|-----------|
| t3 | | | | | | |
| L1. | -.0073918 | .0036887 | -2.00 | 0.045 | -.0146313 | -.0001522 |
| L2. | .423496 | .0331993 | 12.76 | 0.000 | .3583377 | .4886542 |
| L3. | -.1981413 | .0359696 | -5.51 | 0.000 | -.2687365 | -.1275461 |
| L4. | .0724363 | .036451 | 1.99 | 0.047 | .0008961 | .1439764 |
| L5. | -.0813267 | .0362508 | -2.24 | 0.025 | -.1524738 | -.0101795 |
| L6. | .1612079 | .0362909 | 4.44 | 0.000 | .089982 | .2324338 |
| L7. | -.2564737 | .0366887 | -6.99 | 0.000 | -.3284804 | -.184467 |
| L8. | .001805 | .0366299 | 0.05 | 0.961 | -.0700863 | .0736962 |
| L9. | .0705703 | .0362659 | 1.95 | 0.052 | -.0006067 | .1417472 |
| L10. | .1423339 | .0362211 | 3.93 | 0.000 | .071245 | .2134227 |
| L11. | -.0837876 | .0364683 | -2.30 | 0.022 | -.1553616 | -.0122135 |
| L12. | .1031842 | .0359034 | 2.87 | 0.004 | .0327189 | .1736496 |
| L13. | -.1287975 | .033262 | -3.87 | 0.000 | -.1940787 | -.0635163 |
| _cons | .0286559 | .0181922 | 1.58 | 0.116 | -.0070488 | .0643605 |

- The t for L1.t3 is -2
- Ignore reported p-value, compare with table

Interest Rate Spread



ADF test for Spread

```
. dfuller spread12, lags(12)
```

Augmented Dickey-Fuller test for unit root Number of obs = 671

| | Test Statistic | 1% critical value | Interpolated Dickey-Fuller 5% critical value | 10% critical value |
|------------------|-------------------|----------------------|--|-----------------------|
| <hr/> z(t) <hr/> | -4.816 | -3.430 | -2.860 | -2.570 |

Mackinnon approximate p-value for z(t) = 0.0001

- The test of -4.8 is smaller than the critical value
- The p-value of .0001 is much smaller than 0.05
- We reject the hypothesis of a unit root
- We find evidence that the spread is stationary

Testing for a unit Root with Trend

- If the series has a trend

$$\Delta y_t = \hat{\alpha} + \hat{\rho}y_{t-1} + \hat{\gamma}t + \hat{\beta}_1\Delta y_{t-1} + \cdots + \hat{\beta}_k\Delta y_{t-k} + \hat{e}_t$$

- Again test for $\rho=0$.
- **dfuller y, trend lags(2)**

Example: Log(RGDP)

- ADF with 2 lags

```
. dfuller y, trend lags(2)
```

Augmented Dickey-Fuller test for unit root Number of obs = 249

| | Test Statistic | 1% Critical Value | Interpolated Dickey-Fuller 5% Critical Value | 10% Critical Value |
|------------|-------------------|----------------------|--|-----------------------|
| <hr/> z(t) | -2.604 | -3.990 | -3.430 | -3.130 |

MacKinnon approximate p-value for z(t) = 0.2779

- The p-value is not significant.
- We do not reject the hypothesis of a unit root
- Consistent with forecasting growth rates, not levels.

Unit Root Tests in Practice

- Examine your data.
 - Is it trended?
 - Does it appear stationary?
- If it may be non-stationary, apply ADF test
 - Include time trend if trended
- If test rejects hypothesis of a unit root
 - The evidence is that the series is stationary
- If the test fails to reject
 - The evidence is not conclusive
 - Many users then treat the series as if it has a unit root
 - Difference the data, forecast changes or growth rates

Spurious Regression

- One problem caused by unit roots is that it can induce *spurious correlation* among time series
 - Clive Granger and Paul Newbold (1974)
 - Observed the phenomenon
 - Paul Newbold a UW PhD (1970)
 - Peter Phillips (1987)
 - Invented the theory



Spurious Regression

- Suppose you have two independent time-series y_t and x_t
- Suppose you regress y_t on x_t
- Since they are independent, you should expect a zero coefficient on x_t and an insignificant t-statistics, right?

Example

Two independent Random Walks



Regression of y on x

. reg y x

| Source | SS | df | MS | | | |
|----------|------------|-----|------------|-----------------|--------|--|
| Model | 21379.9809 | 1 | 21379.9809 | Number of obs = | 500 | |
| Residual | 31322.7492 | 498 | 62.8970868 | F(1, 498) = | 339.92 | |
| Total | 52702.7302 | 499 | 105.616694 | Prob > F = | 0.0000 | |
| | | | | R-squared = | 0.4057 | |
| | | | | Adj R-squared = | 0.4045 | |
| | | | | Root MSE = | 7.9308 | |

| y | Coef. | Std. Err. | t | P> t | [95% Conf. Interval] | |
|-------|-----------|-----------|-------|-------|----------------------|----------|
| x | .6096435 | .0330664 | 18.44 | 0.000 | .5446765 | .6746104 |
| _cons | -1.062265 | .7635661 | -1.39 | 0.165 | -2.562473 | .437943 |

- X has an estimated coefficient of .6
- A t-statistic of 18! Highly significant!
- But x and y are independent!

Spurious Regression

- This is not an accident
- It happens whenever you regress a random walk on another.
- Traditional implication:
 - Don't regress levels on levels
 - First difference your data
- Even better
 - Make sure your dynamic specification is correct
 - Include lags of your dependent variable

Dynamic Regression

- Regress y on lagged y , plus x

. reg y L.y x

| Source | SS | df | MS | | | |
|----------|------------|-----|------------|-----------------|----------|--|
| Model | 52032.1184 | 2 | 26016.0592 | Number of obs = | 499 | |
| Residual | 487.205408 | 496 | .982268967 | F(2, 496) = | 26485.68 | |
| Total | 52519.3238 | 498 | 105.46049 | Prob > F = | 0.0000 | |
| | | | | R-squared = | 0.9907 | |
| | | | | Adj R-squared = | 0.9907 | |
| | | | | Root MSE = | .99109 | |

| | Coef. | Std. Err. | t | P> t | [95% Conf. Interval] | |
|-------|-----------|-----------|--------|-------|----------------------|----------|
| y | | | | | | |
| L1. | .9917958 | .0055978 | 177.18 | 0.000 | .9807974 | 1.002794 |
| x | .0059606 | .0053662 | 1.11 | 0.267 | -.0045827 | .0165038 |
| _cons | -.0458114 | .0960418 | -0.48 | 0.634 | -.2345104 | .1428875 |

- Now x has insignificant t-statistic, and much smaller coefficient estimate
- Coefficient estimate on lagged y is close to 1.

Message

- If your data might have a unit root
 - Try an ADF test
 - Consider forecasting differences or growth rates
 - Always include lagged dependent variable when series is highly correlated